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consider the problem of a robot algorithm learning mechanism moving along the real line attempting to locate a particular point to assist the mechanism we assume that it can communicate with an environment oracle which guides it with information regarding the direction in which it should go if the environment is deterministic the problem is the deterministic point location problem which has been studied rather thoroughly 1 in its pioneering version 1 the problem was presented in the setting that the environment could charge the robot a cost which was proportional to the distance it was from the point sought for the question of having multiple communicating robots locate a point on the line has also been studied 1 2 in the stochastic version of this problem we consider the scenario when the learning mechanism attempts to locate a point in an interval with stochastic i e possibly erroneous instead of deterministic responses from the environment thus when it should really be moving to the right it may be advised to move to the left and vice versa apart from the problem being of importance in its own right the stochastic point location problem also has potential applications in solving optimization problems in many optimization solutions for example in image processing pattern recognition and neural computing 5 9 11 12 14 16 19 the algorithm works its way from its current solution to the optimal solution based on information that it currently has a crucial question is one of determining the parameter which the optimization algorithm should use

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