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Robot Control 1991 (SYROCO'91) Zeitschrift Für  
Kristallographie

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Robot Control 1991 (SYROCO'91) 2014-05-23 this volume contains 92 papers on the state of the art in robotics research in this volume topics on modelling and identification are treated first as they build the basis for practically all control aspects then the most basic control tasks are discussed i e problems of inverse kinematics groups of papers follow which deal with various advanced control aspects they range from rather general methods to more specialized topics such as force control and control of hydraulic robots the problem of path planning is addressed and strategies for robots with one arm for mobile robots and for multiple arm robots are presented also covered are computational improvements and software tools for simulation and control the integration of sensors and sensor signals in robot control

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2005-03

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